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Elimination of Intermediate Results in Functional Programs

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Outline

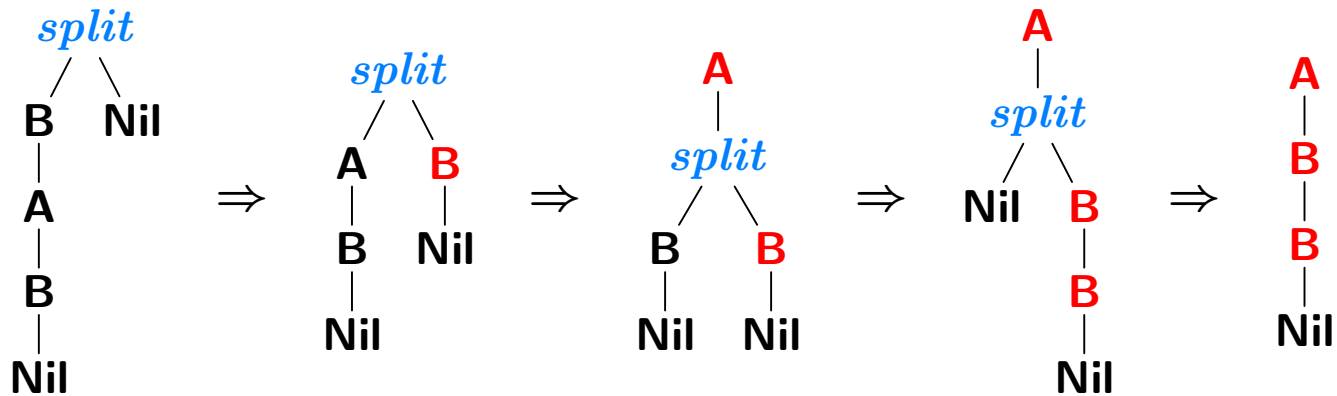
1. Functional programs and intermediate results
2. Deforestation
3. Tree transducer composition
4. Surprise

Why functional programming matters

- declarative specifications, but executable
- no side effects \Rightarrow referential transparency
- clear semantics \Rightarrow equational reasoning
- encourages use of high-level programming constructs
- high potential for modularisation of programs

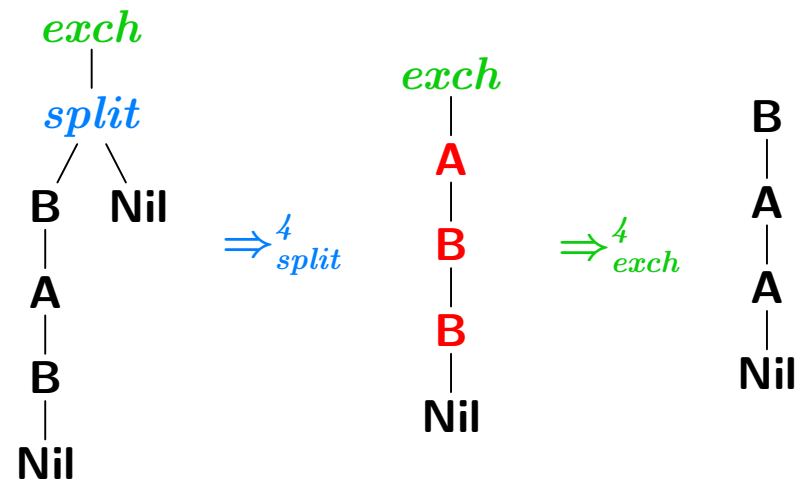
Function definition by structural recursion

```
data List = A List | B List | Nil
split :: List → List → List
split (A u) y = A (split u y)
split (B u) y = split u (B y)
split Nil y = y
```



Modularity vs. efficiency

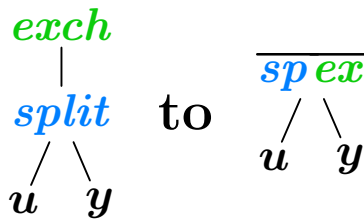
```
exch :: List → List
exch (A v) = B (exch v)
exch (B v) = A (exch v)
exch Nil = Nil
main t = exch (split t Nil)
```



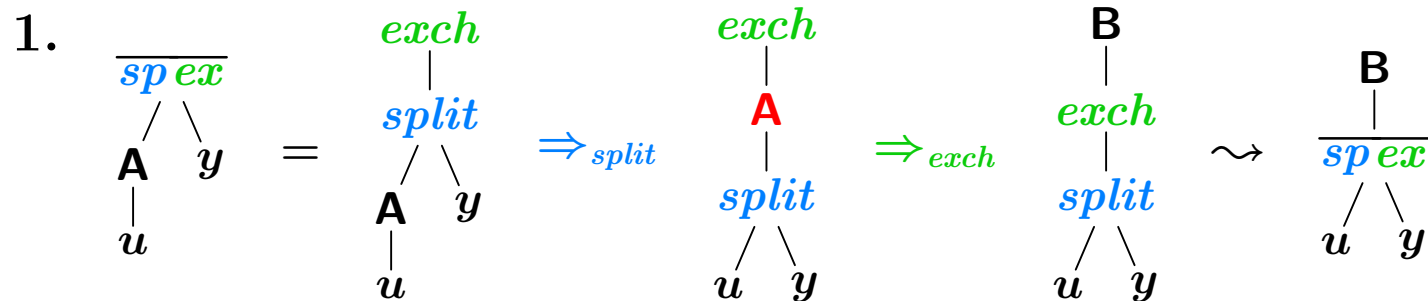
Intermediate results lead to inefficiencies!

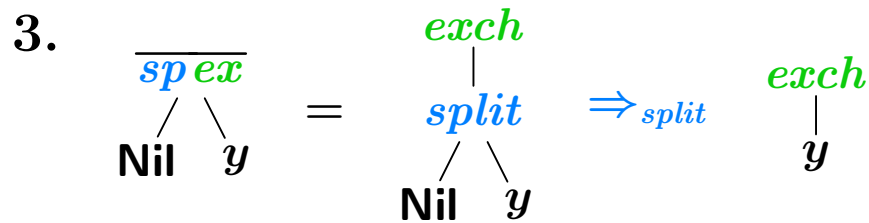
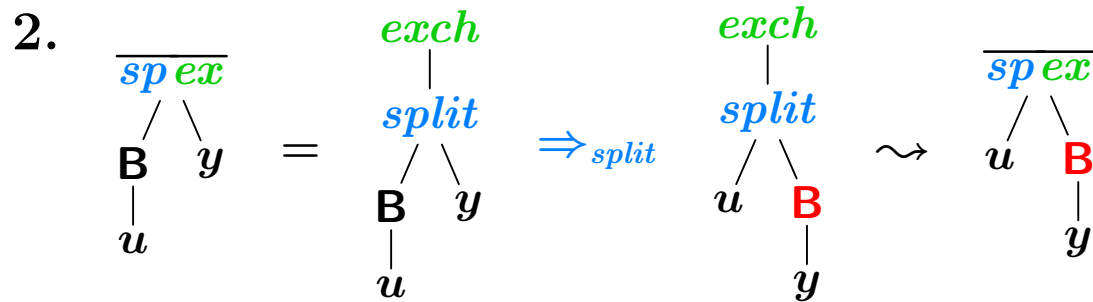
Deforestation [Wadler, 1990]

Key ideas: folding split to $\overline{\text{sp ex}}$ and “translating” right-hand

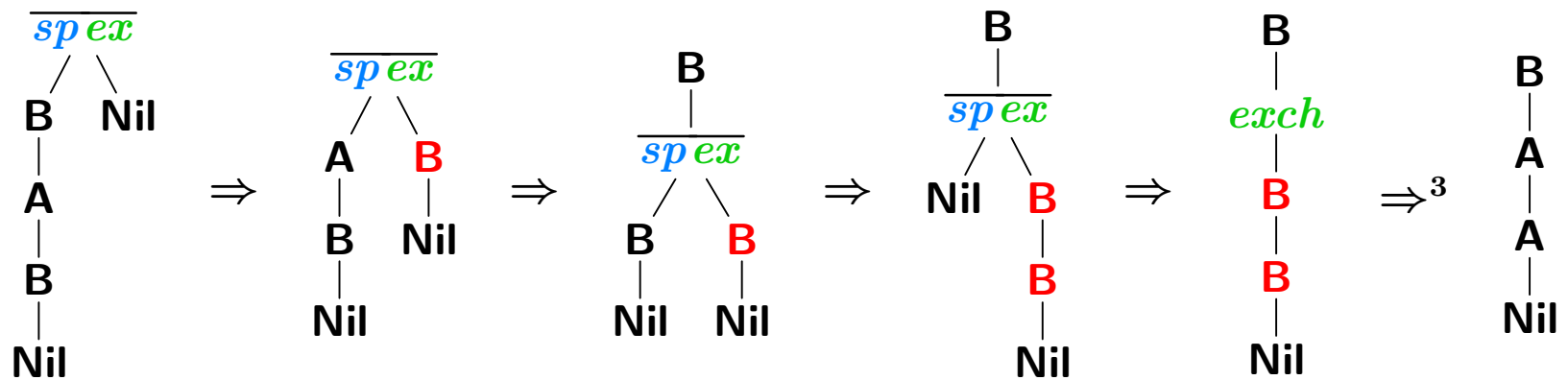


sides of split with rules of exch :





Deforestation eliminated only part of the intermediate result:



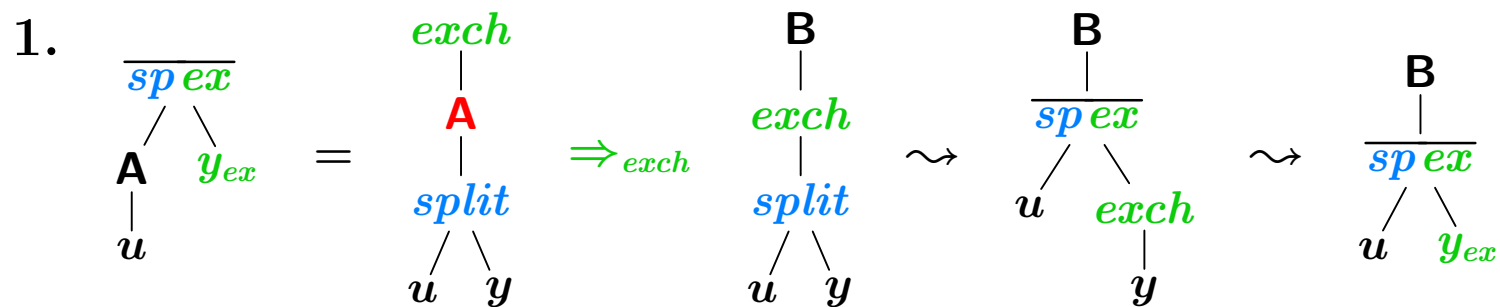
Tree transducer theory comes to the rescue

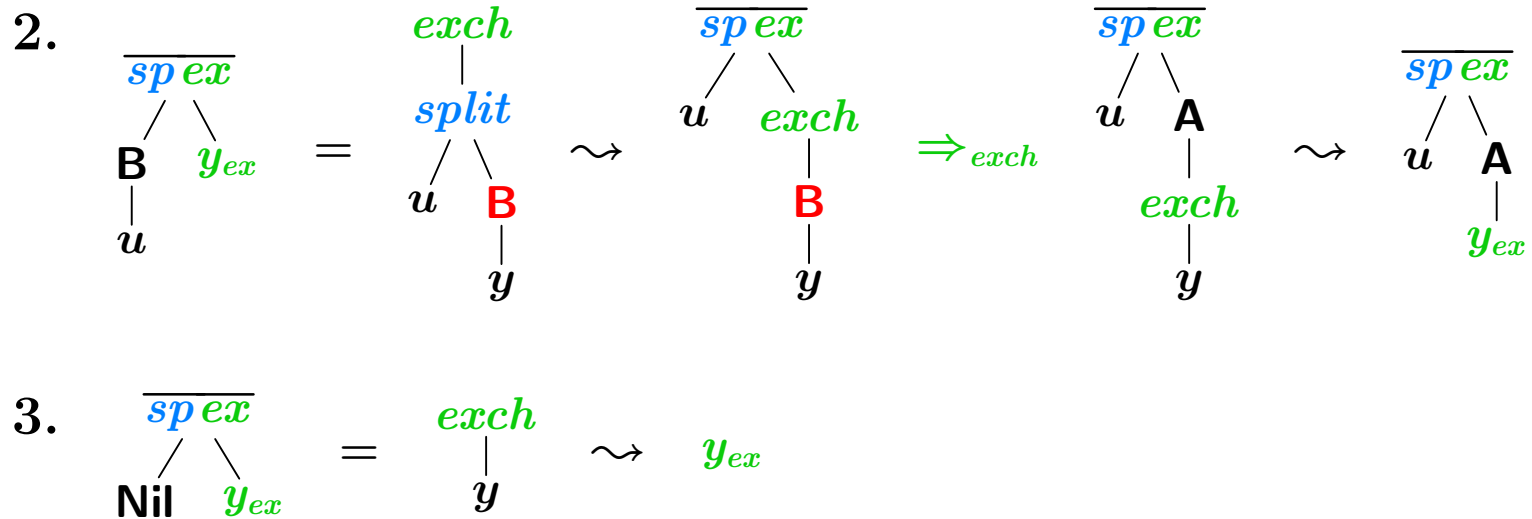
- Tree transducers are:
 - finite devices computing tree translations
(tree automata with output)
 - used as models for syntax-directed semantics
 - used as models for fragments of XML query languages
 - often, special functional programs
- Their theory studies:
 - complexity, decidability issues
 - expressive power of different classes
 - closure under composition

Example: *MAC* ; *TOP* \subseteq *MAC* [Engelfriet & Vogler, 1985]

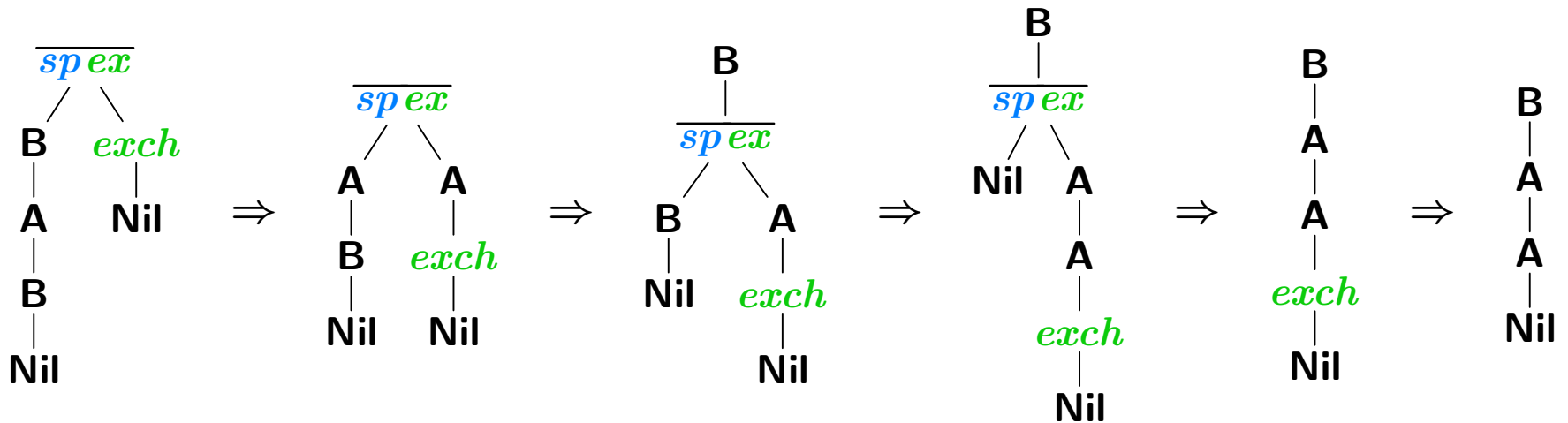
Approach: replace $\begin{array}{c} \textit{exch} \\ | \\ \textit{split} \\ / \quad \backslash \\ u \quad y \end{array}$ by $\begin{array}{c} \overline{\textit{sp ex}} \\ / \quad \backslash \\ u \quad \textit{exch} \\ | \\ y \end{array}$ and hence assume that

$\overline{\textit{sp ex}}$ has as second argument the translation of *split*'s accumulating parameter with *exch*:





Production of intermediate result completely avoided:



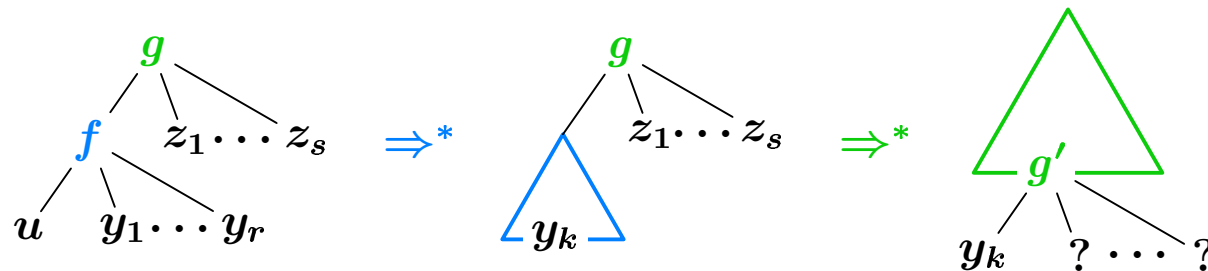
How about more interesting cases?

```

rev :: List → List → List
rev (A v) z = rev v (A z)
rev (B v) z = rev v (B z)
rev Nil z = z
main t = rev (split t Nil) Nil
  
```

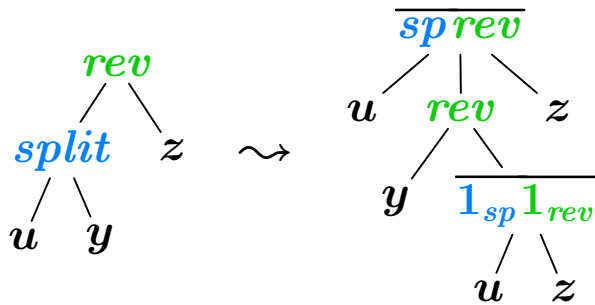
Have to replace $\text{split } z$ by $\overline{\text{sprev}} z$, but how exactly?

In general, what about the values in question in:



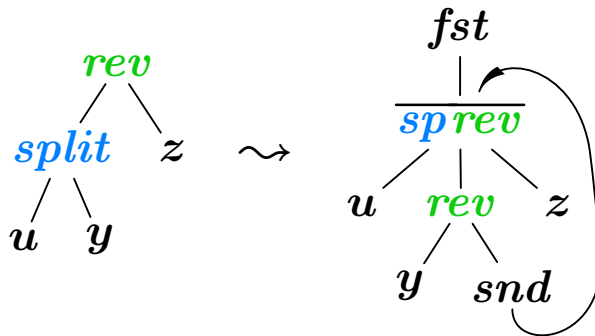
Two solutions

1. Using auxiliary functions:



[V. & Kühnemann] Composition of functions with accumulating parameters. *J. Funct. Prog.*, to appear.

2. Using tupling and circular bindings:



[V.] Using circular programs to deforest in accumulating parameters. *Higher-Order and Symb. Comp.*, to appear.

After post-processing (in both cases):

$$\overline{sprev}' :: \text{List} \rightarrow \text{List} \rightarrow \text{List}$$
$$\overline{sprev}' (\mathbf{A} \ u) \ z = \overline{sprev}' \ u (\mathbf{A} \ z)$$
$$\overline{sprev}' (\mathbf{B} \ u) \ z = \mathbf{B} (\overline{sprev}' \ u \ z)$$
$$\overline{sprev}' \ \text{Nil} \ z = z$$
$$\text{main}' \ t = \overline{sprev}' \ t \ \text{Nil}$$

What about efficiency?

```

data Nat = S Nat | Z
div, div' :: Nat → Nat
div (S u) = div' u
div Z = Z
div' (S u) = S (div u)
div' Z = Z
exp :: Nat → Nat → Nat
exp (S v) z = exp v (exp v z)
exp Z z = S z
main t = exp (div t) Z
  
```

~

```


, but



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```

Formal efficiency analysis

- Measure: number of *call-by-need* reduction steps
- Approach:
 - annotate original and composed programs to reflect performed reduction steps in the output
 - push annotation of composed program backwards through the composition construction
 - compare and manipulate resulting annotations of the original program to obtain sufficient criteria

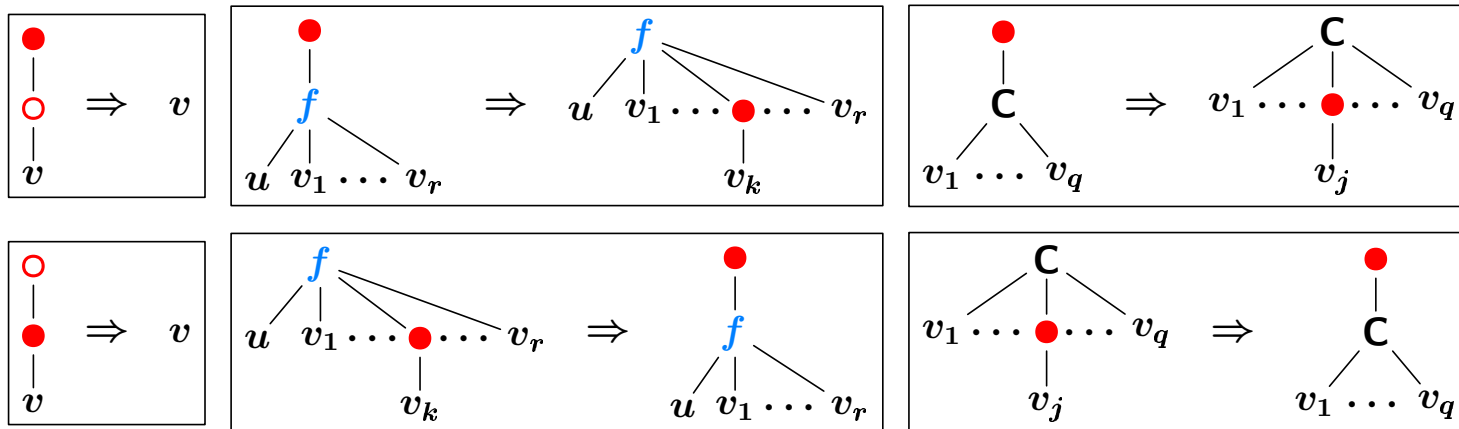
[V.] Conditions for efficiency improvement by tree transducer composition. *Proc. RTA '02*, LNCS 2378.

An Example Criterion at Work

Annotated program:

$split (A u) y = \bullet (A (split u (\circ y)))$	$rev (A v) z = rev v (A z)$
$split (B u) y = split u (\circ (\bullet (B y)))$	$rev (B v) z = rev v (B z)$
$split Nil y = y$	$rev Nil z = z$
$main t = rev (split t (\circ (\bullet Nil))) Nil$	$rev (\circ v) z = \circ (rev v z)$
	$rev (\bullet v) z = \bullet (rev v z)$

Since *split* is *context-linear* and *-nondeleting*, and *rev* is *linear* and *nondeleting*, the following rules may be used with the aim of eliminating all \circ -symbols in the right-hand sides of *split*:



Implementation

Haskell⁺ system

- research tool
- annotated input programs:
beginmag *Split* [Mac]
input Data
syn *split* :: List → List → List
split (A u) y = A (*split* u y)
split (B u) y = *split* u (B y)
split Nil y = y
endmag
- requires user interaction

GHC compiler pass

- prototype implementation
- ordinary Haskell source, e.g.:

split x y = case x of
 A u → A (*split* u y)
 B u → *split* u (B y)
 Nil → y
- integration as an optimization pass in compiler pipeline

Deaccumulation

Surprise: sometimes it is a good idea to transform an efficient program into an inefficient one.

$$\begin{aligned} \mathit{split} (\mathbf{A} \ u) \ y &= \mathbf{A} (\mathit{split} \ u \ y) \\ \mathit{split} (\mathbf{B} \ u) \ y &= \mathit{split} \ u \ (\mathbf{B} \ y) \\ \mathit{split} \ \mathbf{Nil} \ y &= y \\ \mathit{main} \ t &= \mathit{split} \ t \ \mathbf{Nil} \end{aligned}$$

linear runtime

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$$\begin{aligned} \mathit{split}' (\mathbf{A} \ u) &= \mathbf{A} (\mathit{split}' \ u) \\ \mathit{split}' (\mathbf{B} \ u) &= \mathit{app} (\mathit{split}' \ u) (\mathbf{B} \ \mathbf{Nil}) \\ \mathit{split}' \ \mathbf{Nil} &= \mathbf{Nil} \\ \mathit{app} (\mathbf{A} \ u) \ y &= \mathbf{A} (\mathit{app} \ u \ y) \\ \mathit{app} (\mathbf{B} \ u) \ y &= \mathbf{B} (\mathit{app} \ u \ y) \\ \mathit{app} \ \mathbf{Nil} \ y &= y \\ \mathit{main}' \ t &= \mathit{split}' \ t \end{aligned}$$

quadratic runtime

Why?

Improving Provability

Proving idempotence of the original program, i.e.,

$$\mathit{split} (\mathit{split} t \text{ Nil}) \text{ Nil} = \mathit{split} t \text{ Nil},$$

by induction on t requires a generalization that is difficult to find automatically.

In contrast, an inductive proof of

$$\mathit{split}' (\mathit{split}' t) = \mathit{split}' t$$

is much easier.

[Giesl, Kühnemann & V.] Deaccumulation — Improving Provability. *Proc. ASIAN'03*, LNCS, to appear.

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